Robot Introduction: Initial Observations

|  | Task | Question | Answer |
| :---: | :---: | :---: | :---: |
| 1 | Drive forward 2 rotations of the wheels | How far did your robot travel? |  |
| 2 | Drive forward 2 degrees of the wheels | How far did your robot travel? |  |
| 3 | Drive forward 2 seconds of the wheels | How far did your robot travel? |  |
| 4 | Set your robot speed to zero and then drive your robot forward 5 rotations and then 1800 degrees backwards. | How far did your robot travel? |  |
| 5 | Drive your robot forward 5 rotations slowly and then 1800 degrees backwards as fast as possible | What speed did you choose to move forward? |  |
|  |  | What speed did you choose to move backwards? |  |
|  |  | Did your robot travel farther going forward or backwards? |  |
| 6 | Make your robot turn around in a complete circle $360^{\circ}$ | Did it work the first time you tried it? | (Yes or No) |
|  |  | How far did your robot turn if you typed $360^{\circ}$ ? |  |
|  |  | What should degrees of the wheel be set to in order to get the robot to turn a complete circle? |  |
| 7 | Drive your robot 20 inches and then turn $180^{\circ}$ and drive back where you started | What did you have to program in order for it to work properly? |  |
|  |  | How much duration was needed to go forward 20 inches? |  |

